

Introduction to Tensor Computation

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2 Tensor Computation (M-Product and t-Product)

- M-Product
- t-Product

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What is tensor?

- Tensor is a type of data structure used in ML to represent various kinds of objects including scalars, vectors, arrays, matrices and other tensors.
- Higher-dimensional generalization of a matrix (multidimensional arrays.)
- The order of a tensor is defined by the number of directions required to describe it.

(11)

5	3	7
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5
1.5
2

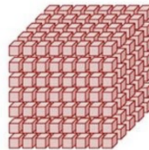
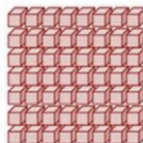
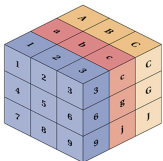
4	19	8
16	3	5

SCALAR

Row Vector
(shape 1x3)

Column Vector
(shape 3x1)

MATRIX





Why Tensor

- Mathematical modeling of problems → solving multilinear systems.
- Standard matrix representation of data analysis is not enough to represent all the information content of the higher dimensional fields.
- Tensor (**multiway arrays**) is a natural representation for massive multidimensional data.

Examples

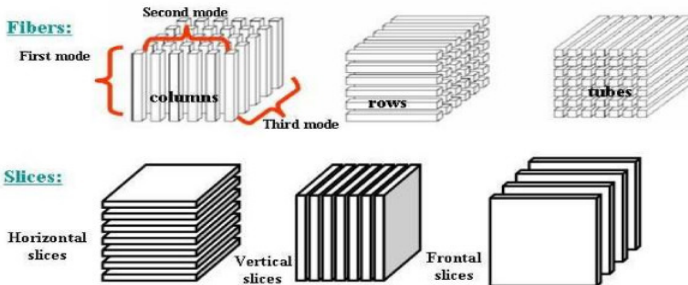
- In a stadium: indexed by **section, row, seat**
- Finance data: indexed by **institute, year, month, day**
- Geographical data: **longitude, latitude, temperature, pressure, rainfall, time.**
- Data on health status: **blood analysis, immune system status, genetic background, nutrition, alcohol-tobacco-drug-consumption, operations.**

Tensor Representations

- The higher order analogue of matrix rows and columns are called fibers.
- A matrix column is a **mode-1 fiber** and a matrix row is a **mode-2 fiber**.

For a third order tensor: x_{ijk}

- We have column $(x_{:jk})$, row $(x_{i:k})$, and tube $(x_{ij:})$ fibers.
- We have horizontal $(x_{i::})$, vertical $(x_{:j:})$ and frontal $(x_{::k})$ slices



Example

Consider a 4th order tensor $\mathcal{A} \in \mathbb{R}^{2 \times 2 \times 2 \times 3}$. Now fixing the 4th index, we can get three $2 \times 2 \times 2$ tensors. The elements of $\mathcal{A}_1, \mathcal{A}_2, \mathcal{A}_3$ are

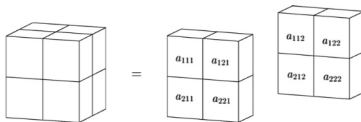
$$\mathcal{A}_1 : a_{1111} \ a_{1211} \ a_{2111} \ a_{2211} \ a_{1121} \ a_{1221} \ a_{2121} \ a_{2221},$$

$$\mathcal{A}_2 : a_{1112} \ a_{1212} \ a_{2112} \ a_{2212} \ a_{1122} \ a_{1222} \ a_{2122} \ a_{2222},$$

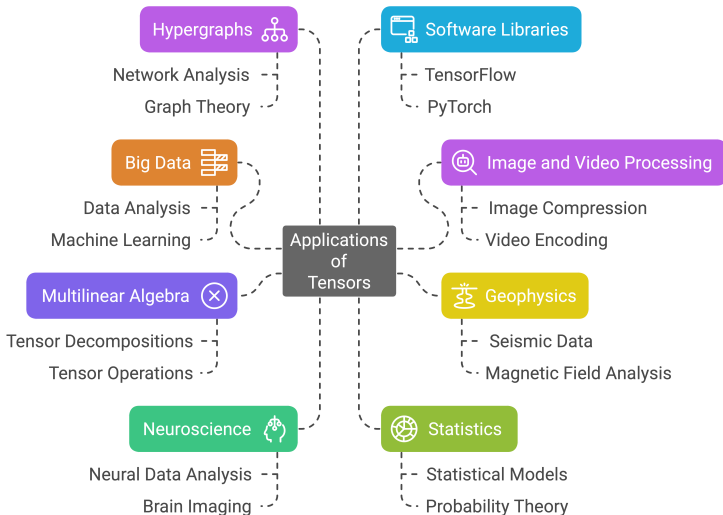
$$\mathcal{A}_3 : a_{1113} \ a_{1213} \ a_{2113} \ a_{2213} \ a_{1123} \ a_{1223} \ a_{2123} \ a_{2223},$$

A third-order tensor $\mathcal{A} \in \mathbb{R}^{2 \times 2 \times 2}$ looks like a **cube** of data, but the orientation of third-order tensors is not unique, i.e.,

$$(\mathcal{A})_{ij,1} \text{ and } (\mathcal{A})_{i,j,2} \text{ or } (\mathcal{A})_{1,i,j} \text{ and } (\mathcal{A})_{2,i,j} \text{ or } (\mathcal{A})_{i,1,j} \text{ and } (\mathcal{A})_{i,2,j}$$



Applications of Tensors in Various Domains



Introduction and
Motivation

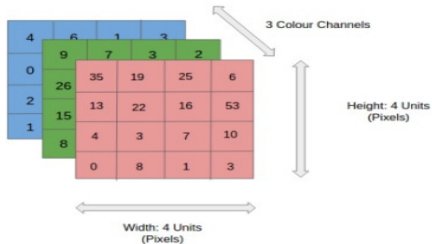
Tensor Computation
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Image Applications

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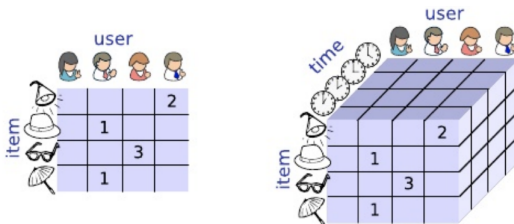


Example (Color Videos)



Example (Relational Data)

Relational data is a collection of relations among multiple objects



Relationship of pair $\iff$ Matrix (2 dim array)

Relationships of 3-tuple $\iff$ Tensor (3 dim array)

Tensor

Tensor representation is generally high-dimensional and large-scale.

EX: 1000 users $\times$ 1000 items $\times$ 1000 times = total 10^9 relationship

AIM $\longrightarrow$ To develop tensor based model for the applications

- Efficiency, scalability, productivity, and reliability

Tensor Computations

Let $A \in \mathbb{R}^{m \times n}$ and $B \in \mathbb{R}^{n \times p}$, then $C = AB \in \mathbb{R}^{m \times p}$

$$c_{ij} = \sum_{k=1}^{k=n} a_{ik} b_{kj}, \text{ for } 1 \leq i \leq m, 1 \leq j \leq n,$$

- Suppose $\mathcal{A} = (a_{i_1 \dots i_p}) \in \mathbb{R}^{n_1 \times \dots \times n_p}$, $p > 2$ be the tensor of order p

Here, if p is even (odd), then $\mathcal{A}$ is an even (odd) order tensor.

- Let $\mathcal{A} = (a_{ijk}) \in \mathbb{R}^{3 \times 2 \times 3}$, $\mathcal{B} = (b_{ijk}) \in \mathbb{R}^{2 \times 3 \times 3}$

Theory/Computation/Application of Tensors

- | | |
|-------------------------|------------------------------------|
| ➤ Tensor Multiplication | ➤ Image Deblurring and Compression |
| ➤ Tensor Decomposition | ➤ Face Recognition |
| ➤ Tensor Inverse | ➤ High-Dimensional PDEs |



Progress of Tensor Products

- n-Mode Product (2000): By L. Lathauwer et. al.
- T-Product (2011): By Kilmer and Martin
- Shao-Product (2013): By J. Shao et. al.
- C-Product (2015) & M-product (2015): By Kernfeld et. al.

☞ L. Lathauwer, B. Moor, J. Vandewalle A multilinear singular value decomposition. SIAM J. Matrix Anal. Appl.21(2000), no.4, 1253-1278.

☞ Shao, Jia-Yu. A general product of tensors with applications. Linear Algebra Appl. 2013;439(8):2350-2366.

☞ Kilmer, Misha E., and Carla D. Martin. Factorization strategies for third-order tensors. Linear Algebra Appl. 2011;435(3):641-658.

☞ E. Kernfeld, M. Kilmer, S. Aeron. Tensor-tensor products with invertible linear transforms. Linear Algebra Appl. 2015; 485:545-570.

☞ T. G. Kolda and B. W. Bader. Tensor Decompositions and Applications. SIAM Rev., 51(3):455-500, 2009.



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- 📖 E. Kernfeld, M. Kilmer, S. Aeron. Tensor-tensor products with invertible linear transforms. Linear Algebra Appl. 2015; 485:545-570.
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Tensor Multiplication

Matrix multiplication

If A is an $M \times N$ matrix and B is an $N \times P$ matrix, then

$$AB = \sum_{k=1}^N a_{ik} b_{kj} \quad 1 \leq i \leq M, \quad 1 \leq j \leq P, \quad 1 \leq k \leq N \quad (1)$$

Tensor multiplication (Einstein product)

For $\mathcal{A} \in \mathbb{C}^{I_1 \times \dots \times I_N \times K_1 \times \dots \times K_N}$ and $\mathcal{B} \in \mathbb{C}^{K_1 \times \dots \times K_N \times J_1 \times \dots \times J_M}$, the Einstein product of tensors $\mathcal{A}$ and $\mathcal{B}$ is defined by the operation $*_N$ via

$$(\mathcal{A} *_N \mathcal{B})_{i_1 \dots i_N j_1 \dots j_M} = \sum_{k_1 \dots k_N} a_{i_1 \dots i_N k_1 \dots k_N} b_{k_1 \dots k_N j_1 \dots j_M}. \quad (2)$$

Example: $\mathcal{A} \in \mathbb{R}^{3 \times 4 \times 5 \times 6}$, $\mathcal{B} \in \mathbb{R}^{5 \times 6 \times 7 \times 8}$, then

$$\mathcal{A} *_2 \mathcal{B} = \sum_{j=1}^5 \sum_{k=1}^6 a_{ijkl} b_{klmn}, \quad \text{where } \mathcal{A} *_2 \mathcal{B} \in \mathbb{R}^{3 \times 4 \times 7 \times 8} \quad (3)$$

🇮🇳 🇬🇧 A. Einstein The foundation of the general theory of relativity, *Annals of Physics* (1916).

Definitions

Definition (Transpose)

The transpose of $\mathcal{A} \in \mathbb{R}^{I \times J \times I \times J}$ is a tensor $\mathcal{B}$ which has entries $b_{ijkl} = a_{klij}$. We denote the transpose of $\mathcal{A}$ as $\mathcal{B} = \mathcal{A}^T$.

If $\mathcal{A} \in \mathbb{R}^{I_1 \times I_2 \times \dots \times I_N \times J_1 \times \dots \times J_N}$, then

$(\mathcal{B})_{i_1, i_2, \dots, i_n, j_1, j_2, \dots, j_n} = (\mathcal{A})_{j_1, j_2, \dots, j_n, i_1, i_2, \dots, i_n}^T$ is the transpose of $\mathcal{A}$.

Definition (Symmetric tensor)

A tensor $\mathcal{A} \in \mathbb{R}^{I_1 \times I_2 \times \dots \times I_N \times J_1 \times \dots \times J_N}$ is symmetric if $\mathcal{A} = \mathcal{A}^T$, that is,

$$a_{i_1, i_2, \dots, i_n, j_1, j_2, \dots, j_n} = a_{j_1, j_2, \dots, j_n, i_1, i_2, \dots, i_n}.$$

✉ M. Brazell, N. Li, C. Navasca, et al. Solving multilinear systems via tensor inversion. SIAM J. Matrix Anal Appl. 2013;34(2):542-570.

Example

➤ Let $\mathcal{A} \in \mathbb{R}^{2 \times 2 \times 2 \times 2}$, with entries

$$\mathcal{A}_{:, :, 1, 1} = \begin{bmatrix} 1 & 0 \\ 5 & -1 \end{bmatrix} \mathcal{A}_{:, :, 1, 2} = \begin{bmatrix} 3 & 9 \\ 7 & -3 \end{bmatrix} \mathcal{A}_{:, :, 2, 1} = \begin{bmatrix} 2 & 5 \\ 6 & -2 \end{bmatrix} \mathcal{A}_{:, :, 2, 2} = \begin{bmatrix} 4 & 3 \\ 8 & -4 \end{bmatrix}$$

Then $\mathcal{B} = \mathcal{A}^T$ with entries

$$\mathcal{B}_{:, :, 1, 1} = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix} \mathcal{B}_{:, :, 1, 2} = \begin{bmatrix} 0 & 9 \\ 5 & 3 \end{bmatrix} \mathcal{B}_{:, :, 2, 1} = \begin{bmatrix} 5 & 7 \\ 6 & 8 \end{bmatrix} \mathcal{B}_{:, :, 2, 2} = \begin{bmatrix} -1 & -3 \\ -2 & -4 \end{bmatrix}$$

Definition

Definition (Identity tensor)

The identity tensor $\mathcal{I}$ is $\mathcal{I}_{i_1 i_2 j_1 j_2} = \delta_{i_1 j_1} \delta_{i_2 j_2}$, where $\delta_{lk} = \begin{cases} 1, & l = k \\ 0, & l \neq k. \end{cases}$

It generalizes to an $2N$ th order identity tensor,

$$(\mathcal{I})_{i_1 i_2 \dots i_N j_1 j_2 \dots j_N} = \prod_{k=1}^N \delta_{i_k j_k}. \quad (4)$$

➤ Let $\mathcal{I} \in \mathbb{R}^{2 \times 2 \times 2 \times 2}$, then

$$\mathcal{I}_{::,1,1} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \mathcal{I}_{::,1,2} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \mathcal{I}_{::,2,1} = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \mathcal{I}_{::,2,2} = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

Definition

Definition (Diagonal tensor)

A tensor $\mathcal{D} \in \mathbb{R}^{I \times J \times I \times J}$ is called diagonal if $d_{ijkl} = 0$ when $i \neq k$ and $j \neq l$.

➤ Let $\mathcal{J} \in \mathbb{R}^{2 \times 2 \times 2 \times 2}$, then

$$\mathcal{D}_{::,1,1} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \mathcal{D}_{::,1,2} = \begin{bmatrix} 0 & 2 \\ 0 & 0 \end{bmatrix}, \mathcal{D}_{::,2,1} = \begin{bmatrix} 0 & 0 \\ 3 & 0 \end{bmatrix}, \mathcal{D}_{::,2,2} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$



Tensor computations

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A Common Framework for Tensor Computations

- Turn tensor $\mathcal{A}$ into a matrix A .
- Through matrix computations, discover things about A .
- Draw conclusions about tensor $\mathcal{A}$ based on what is learned about matrix A .

Tensor computations

Definition (Transformation)

Define the transformation $f : \mathbb{T}_{I_1, I_2, I_1, I_2}(\mathbb{R}) \longrightarrow \mathbb{M}_{I_1 I_2, I_1 I_2}(\mathbb{R})$ with $f(\mathcal{A}) = A$ is defined component-wise as

$$(\mathcal{A})_{i_1 i_2 i_1 i_2} \xrightarrow{f} (A)_{[i_1 + (i_2 - 1)I_1][i_1 + (i_2 - 1)I_1]} \quad (5)$$

where $\mathbb{T}_{I_1, I_2, I_1, I_2}(\mathbb{R}) = \{\mathcal{A} \in \mathcal{R}^{I_1 \times I_2 \times I_1 \times I_2} : \det(f(\mathcal{A})) \neq 0\}$ and $A \in \mathbb{M}_{I_1 I_2, I_1 I_2}(\mathbb{R})$.

In general, for $\mathcal{A} \in \mathbb{T}_{I_1, \dots, I_N, J_1, \dots, J_N}(\mathbb{R})$ and $A \in \mathbb{M}_{I_1 \dots I_N, J_1 \dots J_N}(\mathbb{R})$, then

$$(\mathcal{A})_{i_1 i_2 \dots i_N j_1 j_2 \dots j_N} \xrightarrow{f} (A)_{[i_1 + \sum_{k=2}^N (i_k - 1) \prod_{l=1}^{k-1} I_l][j_1 + \sum_{k=2}^N (j_k - 1) \prod_{l=1}^{k-1} J_l]} \quad (6)$$

Theorem-1

Let f be the map defined in (5). Then the following properties hold:

- (1) The map f is a bijection. Moreover, there exists a bijective inverse map $f^{-1} : \mathbb{M}_{I_1 I_2, I_1 I_2}(\mathbb{R}) \rightarrow \mathbb{T}_{I_1, I_2, I_1, I_2}(\mathbb{R})$.
- (2) The map satisfies $f(\mathcal{A} *_2 \mathcal{B}) = f(\mathcal{A}) \cdot f(\mathcal{B})$, where $\cdot$ refers to matrix multiplication

Tensor computations

Consider a tensor $\mathcal{A} = (a_{ijkl}) \in \mathbb{R}^{2 \times 3 \times 2 \times 3}$

$$a_{ij11} = \begin{pmatrix} a_{1111} & a_{1211} & a_{1311} \\ a_{2111} & a_{2211} & a_{2311} \end{pmatrix}, a_{ij12} = \begin{pmatrix} a_{1112} & a_{1212} & a_{1312} \\ a_{2112} & a_{2212} & a_{2312} \end{pmatrix},$$

$$a_{ij13} = \begin{pmatrix} a_{1113} & a_{1213} & a_{1313} \\ a_{2113} & a_{2213} & a_{2313} \end{pmatrix}, a_{ij21} = \begin{pmatrix} a_{1121} & a_{1221} & a_{1321} \\ a_{2121} & a_{2221} & a_{2321} \end{pmatrix},$$

$$a_{ij22} = \begin{pmatrix} a_{1122} & a_{1222} & a_{1322} \\ a_{2122} & a_{2222} & a_{2322} \end{pmatrix}, a_{ij23} = \begin{pmatrix} a_{1123} & a_{1223} & a_{1323} \\ a_{2123} & a_{2223} & a_{2323} \end{pmatrix},$$

$$\mathcal{A} = \begin{bmatrix} a_{1111} & a_{1121} & a_{1112} & a_{1122} & a_{1113} & a_{1123} \\ a_{2111} & a_{2121} & a_{2112} & a_{2122} & a_{2113} & a_{2123} \\ a_{1211} & a_{1221} & a_{1212} & a_{1222} & a_{1213} & a_{1223} \\ a_{2211} & a_{2221} & a_{2212} & a_{2222} & a_{2213} & a_{2223} \\ a_{1311} & a_{1321} & a_{1312} & a_{1322} & a_{1313} & a_{1323} \\ a_{2311} & a_{2321} & a_{2312} & a_{2322} & a_{2313} & a_{2323} \end{bmatrix}$$

Drawback of the Einstein product

Definition (Transformation)

Define the transformation $f : \mathbb{T}_{I_1, I_2, J_1, J_2}(\mathbb{R}) \longrightarrow \mathbb{M}_{I_1 I_2, J_1 J_2}(\mathbb{R})$ with $f(\mathcal{A}) = \mathbf{A}$ is defined component-wise as

$$(\mathcal{A})_{i_1 i_2 i_1 i_2} \xrightarrow{f} (\mathbf{A})_{[i_1 + (i_2 - 1)I_1][i_1 + (i_2 - 1)I_1]} \quad (7)$$

where $\mathcal{A} \in \mathbb{T}_{I_1, I_2, J_1, J_2}(\mathbb{R})$ and $\mathbf{A} \in \mathbb{M}_{I_1 I_2, J_1 J_2}(\mathbb{R})$.

- Using the above Definition the tensor $\mathcal{A} \in \mathbb{R}^{I_1 \times I_2 \times I_1 \times I_2}$, which can be extended only to any square tensor, i.e., for $\mathcal{A} \in \mathbb{R}^{I_1 \times I_2 \times \dots \times I_N \times I_1 \times I_2 \times \dots \times I_N}$.
- But the extension of an arbitrary-order tensor is impossible, since f is not homomorphism for even-order and/or arbitrary-order tensors.
- The Einstein product is not defined for the following two even-order tensors, $\mathcal{A} \in \mathbb{R}^{I_1 \times I_2 \times J_1 \times J_2}$ and $\mathcal{B} \in \mathbb{R}^{I_1 \times I_2 \times J_1 \times J_2}$, i.e., $\mathcal{A} *_2 \mathcal{B}$ is not defined.

📖 R Behera, S Maji, and R. N. Mohapatra, **Weighted Moore-Penrose inverses of arbitrary-order tensors**, *Computational and Applied Mathematics*, (2020), 39:284



Efficient Solution of the Poisson problem

- Consider d -dimensional Poisson equation

$$\begin{aligned}-\nabla^2 u &= f \text{ in } \Omega \subset \mathbb{R}^d \\ u &= 0 \text{ on } \partial\Omega,\end{aligned}$$

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The discretized d -dimensional Poisson equation can be written as follows:

$$Ax = b, \text{ where the matrix } A \in \mathbb{R}^{n^d \times n^d}, \text{ vectors } x, b \in \mathbb{R}^{n^d \times 1}$$

- The traditional matrix- and vector-based approach is **impractical to solve**

Example: Tensor representation of the 3D Poisson problem

Consider $d = 3$ and interior grid points $n = 100$ with Dirichlet boundary condition, then we obtain matrix $A \in \mathbb{R}^{10^6 \times 10^6}$, vectors $x \in \mathbb{R}^{10^6 \times 1}$ and $b \in \mathbb{R}^{10^6 \times 1}$.

$$\mathcal{A} * \mathcal{X} = \mathcal{B}, \mathcal{A} \in \mathbb{R}^{100 \times 100 \times 100 \times 100 \times 100 \times 100}, \mathcal{X} \in \mathbb{R}^{100 \times 100 \times 100}, \text{ and } \mathcal{B} \in \mathbb{R}^{100 \times 100 \times 100},$$

Ref: **R. Behera, A. Nandi, J. Sahoo.** Further results on the Drazin inverse of even-order tensors.

Numer Linear Algebra Appl. (2020) e2317. DOI: 10.1002/nla.2317



Poisson problem

Multilinear systems in Poisson problems

Consider the two-dimension Poisson problem on $\Omega = \{(x, y) : 0 < x, y < 1\}$ with boundary $\partial\Omega$. For a given function $f(x, y)$ we have

$$\begin{aligned} -\frac{\partial^2 u}{\partial x^2} - \frac{\partial^2 u}{\partial y^2} &= f(x, y) \text{ in } \Omega \\ u &= 0 \text{ on } \partial\Omega, \end{aligned}$$

Using 5-point stencil central difference scheme on a discretizing the unit square domain with n interior nodes, we obtain the following multilinear system

$$\mathcal{A} *_2 \mathcal{X} = \mathcal{B}, \quad \text{where } \mathcal{A} \in \mathbb{R}^{n \times n \times n \times n}, \mathcal{X} \in \mathbb{R}^{n \times n}, \text{ and } \mathcal{B} \in \mathbb{R}^{n \times n},$$

where the tensor $\mathcal{A}$ is of the form $\mathcal{A} = \mathcal{I}_n \otimes \mathcal{P}_n + \mathcal{P}_n \otimes \mathcal{I}_n, \quad (8)$

Here $\mathcal{I}_n$ is the second order identity tensor and $\mathcal{P}_n$ is also a second order tensor of the form, $\mathcal{P}_n = \text{tridiagonal}(-1, 2, -1)$.

Poisson problem

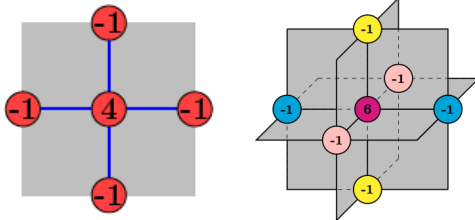


Figure: 5-point Stencil and 7-point Stencil

By applying 7-point stencil formula for 3-dimensional Poisson equation with same boundary conditions, we obtain the following tensor equation

$$\mathcal{A} *_3 \mathcal{X} = \mathcal{B}, \mathcal{A} \in \mathbb{R}^{n \times n \times n \times n \times n \times n}, \mathcal{X} \in \mathbb{R}^{n \times n \times n}, \text{ and } \mathcal{B} \in \mathbb{R}^{n \times n \times n},$$

$$\text{where } \mathcal{A} = \mathcal{P}_n \otimes \mathcal{I}_n \otimes \mathcal{I}_n + \mathcal{I}_n \otimes \mathcal{P}_n \otimes \mathcal{I}_n + \mathcal{I}_n \otimes \mathcal{I}_n \otimes \mathcal{P}_n. \quad (9)$$

Poisson problem

Extending, the same idea to 4-dimensional Poisson problem, we obtain the following multilinear system

$$\mathcal{A} *_4 \mathcal{X} = \mathcal{B}, \mathcal{A} \in \mathbb{R}^{\overbrace{n \times \cdots \times n}^{8 \text{ times}}}, \mathcal{X} \in \mathbb{R}^{n \times n \times n \times n}, \text{ and } \mathcal{B} \in \mathbb{R}^{n \times n \times n \times n},$$

where the tensor $\mathcal{A}$ is the following form

$$\begin{aligned} \mathcal{A} = & \mathcal{P}_n \otimes \mathcal{I}_n \otimes \mathcal{I}_n \otimes \mathcal{I}_n + \mathcal{I}_n \otimes \mathcal{P}_n \otimes \mathcal{I}_n \otimes \mathcal{I}_n \\ & + \mathcal{I}_n \otimes \mathcal{I}_n \otimes \mathcal{P}_n \otimes \mathcal{I}_n + \mathcal{I}_n \otimes \mathcal{I}_n \otimes \mathcal{I}_n \otimes \mathcal{P}_n. \end{aligned}$$

In the light of the above Eqs (8), (9) and (10) one can generate the tensor $\mathcal{A}$ to solve higher dimensional Poisson problem.



Introduction and
Motivation

Tensor Computation
(M-Product and
t-Product)

M-Product

t-Product

Image Applications

References

1 Introduction and Motivation

2 Tensor Computation (M-Product and t-Product)

- M-Product

- t-Product

3 Image Applications

4 References

Unfolding of a 3rd order Tensor

➤ Let $\mathcal{A} \in \mathbb{R}^{3 \times 4 \times 2}$, with entries (frontal slices)

$$\mathcal{A}(:, :, 1) = \begin{bmatrix} 1 & 4 & 7 & 10 \\ 2 & 5 & 8 & 11 \\ 3 & 6 & 9 & 12 \end{bmatrix}, \mathcal{A}(:, :, 2) = \begin{bmatrix} 13 & 16 & 19 & 22 \\ 14 & 17 & 20 & 23 \\ 15 & 18 & 21 & 24 \end{bmatrix}.$$

■ Mode-1 unfolding of $\mathcal{A}$ is a matrix of order 3×8 and entries are given by

$$\begin{bmatrix} 1 & 4 & 7 & 10 & 13 & 16 & 19 & 22 \\ 2 & 5 & 8 & 11 & 14 & 17 & 20 & 23 \\ 3 & 6 & 9 & 12 & 15 & 18 & 21 & 24 \end{bmatrix}$$

■ Mode-2 unfolding of $\mathcal{A}$ is a matrix of order 2×6 and entries are given by

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- Mode-3 unfolding of $\mathcal{A}$ is a matrix of order 2×12 and entries are given by

$$A_{(3)} = \begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 \\ 13 & 14 & 15 & 16 & 17 & 18 & 19 & 20 & 21 & 22 & 23 & 24 \end{bmatrix}$$

Unfolding of a 3rd order Tensor

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- Mode-3 unfolding of $\mathcal{A}$ is a matrix of order 2×12 and entries are given by

$$A_{(3)} = \begin{vmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 \\ 13 & 14 & 15 & 16 & 17 & 18 & 19 & 20 & 21 & 22 & 23 & 24 \end{vmatrix}$$

3-Mode Product

Definition

Let $\mathcal{A} \in \mathbb{R}^{m \times n \times p}$ be a tensor and $M \in \mathbb{R}^{p \times p}$ be a matrix. The 3-mode product of $\mathcal{A}$ with M is denoted by $\mathcal{A} \times_3 M \in \mathbb{R}^{m \times n \times p}$ and element-wise defined as

$$(\mathcal{A} \times_3 B)_{ijk} = \sum_{s=1}^p a_{ijs} b_{ks} \quad i = 1, 2, \dots, m, j = 1, 2, \dots, n, k = 1, 2, \dots, p.$$

Note: From here onwards we will assume M to be invertible.

📖 Kolda, Tamara G., and Brett W. Bader. Tensor decompositions and applications. SIAM review. 2009; 51(3):455-500.

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3-Mode Product

Example

Let $\mathcal{A} \in \mathbb{R}^{2 \times 2 \times 2}$ with entries

$$\mathcal{A}(:, :, 1) = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix}, \mathcal{A}(:, :, 2) = \begin{bmatrix} 5 & 7 \\ 6 & 8 \end{bmatrix}, \text{ and } M = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

$$\text{Evaluate: } MA_{(3)} = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 10 & 12 & 14 & 16 \end{bmatrix}$$

Now $\mathcal{B} = \mathcal{A} \times_3 M \in \mathbb{R}^{2 \times 2 \times 2}$ with entries

$$\mathcal{B}(:, :, 1) = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix}, \mathcal{B}(:, :, 2) = \begin{bmatrix} 10 & 14 \\ 12 & 16 \end{bmatrix}.$$

3-Mode Product

Example

Let $\mathcal{A} \in \mathbb{R}^{2 \times 2 \times 2}$ with entries

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Face-wise Product

Tensor-Tensor Multiplication:

Definition

Let $\mathcal{A} \in \mathbb{R}^{m \times n \times p}$ and $\mathcal{B} \in \mathbb{R}^{n \times k \times p}$ be two tensors. The face-wise product of $\mathcal{A}$ and $\mathcal{B}$ is denoted by $\mathcal{A} \triangle \mathcal{B} \in \mathbb{R}^{m \times k \times p}$ and element-wise defined as

$$(\mathcal{A} \triangle \mathcal{B})(:,:,i) = \mathcal{A}(:,:,i)\mathcal{B}(:,:,i), \quad i = 1, 2, \dots, p.$$

👉 E. Kernfeld, M. Kilmer, S. Aeron. **Tensor-tensor products with invertible linear transforms**. Linear Algebra Appl. 2015; 485:545-570.



Face-wise Product

Example Let $\mathcal{A} \in \mathbb{R}^{2 \times 3 \times 2}$ and $\mathcal{B} \in \mathbb{R}^{3 \times 2 \times 2}$ with respective frontal slices are

$$\mathcal{A}(:, :, 1) = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}, \mathcal{B}(:, :, 1) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \\ 1 & 1 \end{bmatrix}$$
$$\mathcal{A}(:, :, 2) = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \mathcal{B}(:, :, 2) = \begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 1 & 0 \end{bmatrix}.$$

Thus we have $(\mathcal{A} \triangle \mathcal{B})(:, :, 1) = \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix}$ and $(\mathcal{A} \triangle \mathcal{B})(:, :, 2) = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}$.

Face-wise Product

Example Let $\mathcal{A} \in \mathbb{R}^{2 \times 3 \times 2}$ and $\mathcal{B} \in \mathbb{R}^{3 \times 2 \times 2}$ with respective frontal slices are

$$\mathcal{A}(:, :, 1) = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}, \mathcal{B}(:, :, 1) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \\ 1 & 1 \end{bmatrix}$$

$$\mathcal{A}(:, :, 2) = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \mathcal{B}(:, :, 2) = \begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 1 & 0 \end{bmatrix}.$$

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M-Product

Tensor-Tensor Multiplication:

Definition

Let $\mathcal{A} \in \mathbb{R}^{m \times n \times p}$ and $\mathcal{B} \in \mathbb{R}^{n \times k \times p}$ be two tensors and $M \in \mathbb{R}^{p \times p}$. The M-product of $\mathcal{A}$ and $\mathcal{B}$ is denoted by $\mathcal{A} *_M \mathcal{B} \in \mathbb{R}^{m \times k \times p}$ and defined as

$$\mathcal{A} *_M \mathcal{B} = [(\mathcal{A} \times_3 M) \triangle (\mathcal{B} \times_3 M)] \times_3 M^{-1}.$$

🔗 E. Kernfeld, M. Kilmer, S. Aeron. **Tensor-tensor products with invertible linear transforms**. Linear Algebra Appl. 2015; 485:545-570.

Algorithm for M-Product

Algorithm 1: M-Product of $\mathcal{A}$ and $\mathcal{B}$

- 1 **Input** $\mathcal{A} \in \mathbb{R}^{m \times n \times p}$, $\mathcal{B} \in \mathbb{R}^{n \times k \times p}$ and $M \in \mathbb{R}^{p \times p}$.
 - 2 **Compute** $\tilde{\mathcal{A}} = \mathcal{A} \times_3 M$, $\tilde{\mathcal{B}} = \mathcal{B} \times_3 M$
 - 3 **for** $i \leftarrow 1$ to p **do**
 - 4 $\tilde{\mathcal{C}}(:, :, i) = \tilde{\mathcal{A}}(:, :, i) \tilde{\mathcal{B}}(:, :, i)$
 - 5 **end for**
 - 6 **Compute** $\mathcal{C} = \tilde{\mathcal{C}} \times_3 M^{-1}$
 - 7 **return** $\mathcal{C} = \mathcal{A} *_M \mathcal{B}$
-

Note: From here onwards, we will use the tilde notation with respect to M (for example $\tilde{\mathcal{A}} = \mathcal{A} \times_3 M$).

Algorithm for M-Product

Algorithm 2: M-Product of $\mathcal{A}$ and $\mathcal{B}$

- 1 **Input** $\mathcal{A} \in \mathbb{R}^{m \times n \times p}$, $\mathcal{B} \in \mathbb{R}^{n \times k \times p}$ and $M \in \mathbb{R}^{p \times p}$.
 - 2 **Compute** $\tilde{\mathcal{A}} = \mathcal{A} \times_3 M$, $\tilde{\mathcal{B}} = \mathcal{B} \times_3 M$
 - 3 **for** $i \leftarrow 1$ to p **do**
 - 4 $\mathcal{C}(:, :, i) = \tilde{\mathcal{A}}(:, :, i) \tilde{\mathcal{B}}(:, :, i)$
 - 5 **end for**
 - 6 **Compute** $\mathcal{C} = \mathcal{C} \times_3 M^{-1}$
 - 7 **return** $\mathcal{C} = \mathcal{A} *_M \mathcal{B}$
-

Note: From here onwards, we will use the tilde notation with respect to M (for example $\tilde{\mathcal{A}} = \mathcal{A} \times_3 M$).

Algorithm for M-Product

Algorithm 3: M-Product of $\mathcal{A}$ and $\mathcal{B}$

- 1 **Input** $\mathcal{A} \in \mathbb{R}^{m \times n \times p}$, $\mathcal{A} \in \mathbb{R}^{n \times k \times p}$ and $M \in \mathbb{R}^{p \times p}$.
 - 2 **Compute** $\tilde{\mathcal{A}} = \mathcal{A} \times_3 M$, $\tilde{\mathcal{B}} = \mathcal{B} \times_3 M$
 - 3 **for** $i \leftarrow 1$ to p **do**
 - 4 $\tilde{\mathcal{C}}(:, :, i) = \tilde{\mathcal{A}}(:, :, i) \tilde{\mathcal{B}}(:, :, i)$
 - 5 **end for**
 - 6 **Compute** $\mathcal{C} = \tilde{\mathcal{C}} \times_3 M^{-1}$
 - 7 **return** $\mathcal{C} = \mathcal{A} *_M \mathcal{B}$
-

Note: From here onwards, we will use the tilde notation with respect to M (for example $\tilde{\mathcal{A}} = \mathcal{A} \times_3 M$).

Algorithm for M-Product

Algorithm 4: M-Product of $\mathcal{A}$ and $\mathcal{B}$

- 1 **Input** $\mathcal{A} \in \mathbb{R}^{m \times n \times p}$, $\mathcal{A} \in \mathbb{R}^{n \times k \times p}$ and $M \in \mathbb{R}^{p \times p}$.
 - 2 **Compute** $\tilde{\mathcal{A}} = \mathcal{A} \times_3 M$, $\tilde{\mathcal{B}} = \mathcal{B} \times_3 M$
 - 3 **for** $i \leftarrow 1$ to p **do**
 - 4 $\tilde{\mathcal{C}}(:, :, i) = \tilde{\mathcal{A}}(:, :, i) \tilde{\mathcal{B}}(:, :, i)$
 - 5 **end for**
 - 6 **Compute** $\mathcal{C} = \tilde{\mathcal{C}} \times_3 M^{-1}$
 - 7 **return** $\mathcal{C} = \mathcal{A} *_M \mathcal{B}$
-

Note: From here onwards, we will use the tilde notation with respect to M (for example $\tilde{\mathcal{A}} = \mathcal{A} \times_3 M$).

M-Product(Example)

Let $M = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$, $\mathcal{A}, \mathcal{B} \in \mathbb{R}^{2 \times 2 \times 2}$ with entries

$$\mathcal{A}(:, :, 1) = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \mathcal{A}(:, :, 2) = \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix}, \mathcal{B}(:, :, 1) = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \mathcal{B}(:, :, 2) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

➤ Find $\tilde{\mathcal{A}} = \mathcal{A} \times_3 M \in \mathbb{R}^{2 \times 2 \times 2}$ and $\tilde{\mathcal{B}} = \mathcal{B} \times_3 M \in \mathbb{R}^{2 \times 2 \times 2}$ with entries

$$\tilde{\mathcal{A}}(:, :, 1) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \tilde{\mathcal{A}}(:, :, 2) = \begin{bmatrix} 0 & 0 \\ 2 & 2 \end{bmatrix}, \tilde{\mathcal{B}}(:, :, 1) = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \tilde{\mathcal{B}}(:, :, 2) = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}.$$

$$(\tilde{\mathcal{A}} \triangle \tilde{\mathcal{B}})(:, :, 1) = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, (\tilde{\mathcal{A}} \triangle \tilde{\mathcal{B}})(:, :, 2) = \begin{bmatrix} 0 & 0 \\ 4 & 4 \end{bmatrix}.$$

Thus $\mathcal{A} *_M \mathcal{B} = (\tilde{\mathcal{A}} \triangle \tilde{\mathcal{B}}) \times_3 M^{-1}$ is given by

$$\mathcal{A} *_M \mathcal{B}(:, :, 1) = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \text{ and } \mathcal{A} *_M \mathcal{B}(:, :, 2) = \begin{bmatrix} 0 & 0 \\ 2 & 2 \end{bmatrix}$$

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➤ Find $\tilde{\mathcal{A}} = \mathcal{A} \times_3 M \in \mathbb{R}^{2 \times 2 \times 2}$ and $\tilde{\mathcal{B}} = \mathcal{B} \times_3 M \in \mathbb{R}^{2 \times 2 \times 2}$ with entries

$$\tilde{\mathcal{A}}(:, :, 1) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \tilde{\mathcal{A}}(:, :, 2) = \begin{bmatrix} 0 & 0 \\ 2 & 2 \end{bmatrix}, \tilde{\mathcal{B}}(:, :, 1) = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \tilde{\mathcal{B}}(:, :, 2) = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}.$$

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Thus $\mathcal{A} *_M \mathcal{B} = (\tilde{\mathcal{A}} \triangle \tilde{\mathcal{B}}) \times_3 M^{-1}$ is given by

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Definition

Definition (Identity tensor)

Let $\mathcal{A} \in \mathbb{R}^{m \times m \times p}$ and $M \in \mathbb{R}^{p \times p}$. Then $\mathcal{A}$ is called an identity tensor if $\tilde{\mathcal{A}}(:, :, i)$ is an identity matrix of order $m \times m$, for each $i = 1, 2, \dots, p$

➤ Let $\mathcal{A} \in \mathbb{R}^{2 \times 2 \times 2}$ with entries

$$\mathcal{A}(:, :, 1) = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \mathcal{A}(:, :, 2) = \begin{bmatrix} 0.5 & 0 \\ 0 & 0.5 \end{bmatrix} \text{ and } M = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}.$$

Now see the frontal slices of $\tilde{\mathcal{A}} = \mathcal{A} \times_3 M$ that is

$$\tilde{\mathcal{A}}(:, :, 1) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \tilde{\mathcal{A}}(:, :, 2).$$

Definition

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Now see the frontal slices of $\tilde{\mathcal{A}} = \mathcal{A} \times_3 M$ that is

$$\tilde{\mathcal{A}}(:, :, 1) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \tilde{\mathcal{A}}(:, :, 2).$$

Definition

Definition (Identity tensor)

Let $\mathcal{A} \in \mathbb{R}^{m \times m \times p}$ and $M \in \mathbb{R}^{p \times p}$. Then $\mathcal{A}$ is called an identity tensor if $\tilde{\mathcal{A}}(:, :, i)$ is an identity matrix of order $m \times m$, for each $i = 1, 2, \dots, p$

➤ Let $\mathcal{A} \in \mathbb{R}^{2 \times 2 \times 2}$ with entries

$$\mathcal{A}(:, :, 1) = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \mathcal{A}(:, :, 2) = \begin{bmatrix} 0.5 & 0 \\ 0 & 0.5 \end{bmatrix} \text{ and } M = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}.$$

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Definition

Definition (Diagonal tensor)

Let $\mathcal{A} \in \mathbb{R}^{m \times m \times p}$ and $M \in \mathbb{R}^{p \times p}$. Then $\mathcal{A}$ is called diagonal if $\tilde{\mathcal{A}}(:, :, i)$ is diagonal, for each $i = 1, 2, \dots, p$

Definition (Conjugate Transpose)

Let $\mathcal{A} \in \mathbb{R}^{m \times m \times p}$ and $M \in \mathbb{R}^{p \times p}$. The elements of $\mathcal{A}^*$ is obtained as follows: **Compute** $\tilde{\mathcal{A}} = \mathcal{A} \times_3 M$

for $i \leftarrow 1$ **to** p **do**

$\tilde{\mathcal{C}}(:, :, i) = (\tilde{\mathcal{A}}(:, :, i))^*$

end for

Compute $\mathcal{A}^* = \tilde{\mathcal{C}} \times_3 M^{-1}$

Definition

Definition (Diagonal tensor)

Let $\mathcal{A} \in \mathbb{R}^{m \times m \times p}$ and $M \in \mathbb{R}^{p \times p}$. Then $\mathcal{A}$ is called diagonal if $\mathcal{A}(:, :, i)$ is diagonal, for each $i = 1, 2, \dots, p$

Definition (Conjugate Transpose)

Let $\mathcal{A} \in \mathbb{R}^{m \times m \times p}$ and $M \in \mathbb{R}^{p \times p}$. The elements of $\mathcal{A}^*$ is obtained as follows: **Compute** $\tilde{\mathcal{A}} = \mathcal{A} \times_3 M$

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end for

$$\text{Compute } \mathcal{A}^* = \tilde{\mathcal{C}} \times_3 M^{-1}$$

Definition

Let $\mathbf{c} \in \mathbb{R}^n$. If $\mathbf{c} = [c_1, c_2, \dots, c_n]^T$, then the circulant matrix is:

$$\text{Circ}(\mathbf{c}) = \begin{bmatrix} c_1 & c_n & \cdots & c_2 \\ c_2 & c_1 & \cdots & c_3 \\ \vdots & \vdots & \ddots & \vdots \\ c_n & c_{n-1} & \cdots & c_1 \end{bmatrix}$$

Similarly, if $C_1, \dots, C_n$ are $n_1 \times n_2$ real matrices, then

$$\text{Circ}(C_1, \dots, C_n) = \begin{bmatrix} C_1 & C_n & \cdots & C_2 \\ C_2 & C_1 & \cdots & C_3 \\ \vdots & \vdots & \ddots & \vdots \\ C_n & C_{n-1} & \cdots & C_1 \end{bmatrix}.$$

- Let $\mathcal{A} = (a_{i_1 \dots i_p}) \in \mathbb{R}^{n_1 \times \dots \times n_p}$, $p > 1$ be the tensor of order p
- For $(i = 1, \dots, n_p)$, let $\mathcal{A}_i \in \mathbb{R}^{n_1 \times \dots \times n_{p-1}}$ be the tensor of order $(p-1)$.
- Here $\mathcal{A}_i$ is created by holding the p th index of $\mathcal{A}$ fixed at i .

Examples

Consider a 4th order tensor $\mathcal{A} \in \mathbb{R}^{2 \times 2 \times 2 \times 3}$. Now fixing the 4th index of $\mathcal{A}$.

We can get three $2 \times 2 \times 2$ tensors. The elements of $\mathcal{A}_1, \mathcal{A}_2, \mathcal{A}_3$ are

$$\mathcal{A}_1 : a_{1111} \ a_{1211} \ a_{2111} \ a_{2211} \ a_{1121} \ a_{1221} \ a_{2121} \ a_{2221},$$

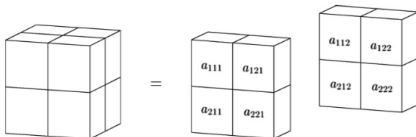
$$\mathcal{A}_2 : a_{1112} \ a_{1212} \ a_{2112} \ a_{2212} \ a_{1122} \ a_{1222} \ a_{2122} \ a_{2222},$$

$$\mathcal{A}_3 : a_{1113} \ a_{1213} \ a_{2113} \ a_{2213} \ a_{1123} \ a_{1223} \ a_{2123} \ a_{2223},$$

A third-order tensor $\mathcal{A} \in \mathbb{R}^{2 \times 2 \times 2}$ looks like a **cube** of data.

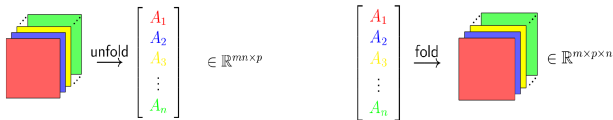
But the orientation of third-order tensors is not unique.

i.e., $(\mathcal{A})_{i,j,1}$ and $(\mathcal{A})_{i,j,2}$ or $(\mathcal{A})_{1,i,j}$ and $(\mathcal{A})_{2,i,j}$ or $(\mathcal{A})_{i,1,j}$ and $(\mathcal{A})_{i,2,j}$.



t-Product

- The **unfold** transforms an $m \times p \times n$ tensor in to $mn \times p$ matrix
- **fold**(.) is the inverse operation, which takes an $mn \times p$ matrix and returns an $m \times p \times n$ tensor. Thus, $\text{fold}(\text{unfold}(\mathcal{A})) = \mathcal{A}$



Product of two tensors $\mathcal{A} \in \mathbb{R}^{m \times p \times n}$ and $\mathcal{B} \in \mathbb{R}^{p \times q \times n}$ is defined as

$$\mathcal{A} * \mathcal{B} = \text{fold}(\text{Circ}(\text{unfold}(\mathcal{A})) * \text{unfold}(\mathcal{B})), \text{ where } \mathcal{A} * \mathcal{B} \in \mathbb{R}^{m \times q \times n}$$

📌 **Example:** Consider two tensors $\mathcal{A} \in \mathbb{R}^{m \times p \times 3}$ and $\mathcal{B} \in \mathbb{R}^{p \times q \times 3}$ then

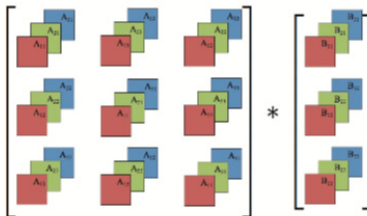
$$\mathcal{A} * \mathcal{B} = \text{fold} \left(\begin{bmatrix} A_1 & A_3 & A_2 \\ A_2 & A_1 & A_3 \\ A_3 & A_2 & A_1 \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ B_3 \end{bmatrix} \right) \in \mathbb{R}^{m \times q \times 3}$$

📌 C. Martin, R. Shafer, and B. Larue. *SIAM J. Sci. Comput.* (2013) 35(1) 474-490.

t-Product

Two fourth-order tensors $\mathcal{A} \in \mathbb{R}^{n_1 \times n_2 \times n_3 \times 3}$ and $\mathcal{B} \in \mathbb{R}^{n_2 \times l \times n_3 \times 3}$ then $\mathcal{A} * \mathcal{B}$ represent as follows

$$\text{unfold}(\mathcal{A}) = \begin{bmatrix} \mathcal{A}_1 \\ \mathcal{A}_2 \\ \mathcal{A}_3 \end{bmatrix} \text{ and } \text{Circ}(\text{unfold}(\mathcal{A})) = \begin{bmatrix} \mathcal{A}_1 & \mathcal{A}_3 & \mathcal{A}_2 \\ \mathcal{A}_2 & \mathcal{A}_1 & \mathcal{A}_3 \\ \mathcal{A}_3 & \mathcal{A}_2 & \mathcal{A}_1 \end{bmatrix}$$



Example of product of two tensors

Let $\mathcal{A} \in \mathbb{R}^{3 \times 3 \times 2 \times 2}$ and $\mathcal{B} \in \mathbb{R}^{3 \times 3 \times 2 \times 2}$ Then

$$\begin{aligned} \mathcal{A} * \mathcal{B} &= \text{fold} \left(\begin{bmatrix} \mathcal{A}_1 & \mathcal{A}_2 \\ \mathcal{A}_2 & \mathcal{A}_1 \end{bmatrix} * \begin{bmatrix} \mathcal{B}_1 \\ \mathcal{B}_2 \end{bmatrix} \right) = \text{fold} \left(\begin{bmatrix} \mathcal{A}_1 * \mathcal{B}_1 + \mathcal{A}_2 * \mathcal{B}_2 \\ \mathcal{A}_2 * \mathcal{B}_1 + \mathcal{A}_1 * \mathcal{B}_2 \end{bmatrix} \right) \\ &= \text{fold} \left(\begin{bmatrix} \text{fold} \left(\begin{bmatrix} \mathcal{A}_{11} & \mathcal{A}_{12} \\ \mathcal{A}_{12} & \mathcal{A}_{11} \end{bmatrix} * \begin{bmatrix} \mathcal{B}_{11} \\ \mathcal{B}_{12} \end{bmatrix} \right) + \text{fold} \left(\begin{bmatrix} \mathcal{A}_{21} & \mathcal{A}_{22} \\ \mathcal{A}_{22} & \mathcal{A}_{21} \end{bmatrix} * \begin{bmatrix} \mathcal{B}_{21} \\ \mathcal{B}_{22} \end{bmatrix} \right) \\ \text{fold} \left(\begin{bmatrix} \mathcal{A}_{21} & \mathcal{A}_{22} \\ \mathcal{A}_{22} & \mathcal{A}_{21} \end{bmatrix} * \begin{bmatrix} \mathcal{B}_{11} \\ \mathcal{B}_{12} \end{bmatrix} \right) + \text{fold} \left(\begin{bmatrix} \mathcal{A}_{11} & \mathcal{A}_{12} \\ \mathcal{A}_{12} & \mathcal{A}_{11} \end{bmatrix} * \begin{bmatrix} \mathcal{B}_{21} \\ \mathcal{B}_{22} \end{bmatrix} \right) \end{bmatrix} \right) \\ &= \text{fold} \left(\begin{bmatrix} \text{fold} \left(\begin{bmatrix} \mathcal{A}_{11} * \mathcal{B}_{11} + \mathcal{A}_{12} * \mathcal{B}_{12} \\ \mathcal{A}_{12} * \mathcal{B}_{11} + \mathcal{A}_{11} * \mathcal{B}_{12} \end{bmatrix} \right) + \text{fold} \left(\begin{bmatrix} \mathcal{A}_{21} * \mathcal{B}_{21} + \mathcal{A}_{22} * \mathcal{B}_{22} \\ \mathcal{A}_{22} * \mathcal{B}_{21} + \mathcal{A}_{21} * \mathcal{B}_{22} \end{bmatrix} \right) \\ \text{fold} \left(\begin{bmatrix} \mathcal{A}_{21} * \mathcal{B}_{11} + \mathcal{A}_{22} * \mathcal{B}_{12} \\ \mathcal{A}_{22} * \mathcal{B}_{11} + \mathcal{A}_{21} * \mathcal{B}_{12} \end{bmatrix} \right) + \text{fold} \left(\begin{bmatrix} \mathcal{A}_{11} * \mathcal{B}_{21} + \mathcal{A}_{12} * \mathcal{B}_{22} \\ \mathcal{A}_{12} * \mathcal{B}_{21} + \mathcal{A}_{11} * \mathcal{B}_{22} \end{bmatrix} \right) \end{bmatrix} \right) \end{aligned}$$

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 &= \text{fold} \left(\begin{bmatrix} \text{fold} \left(\begin{bmatrix} \mathcal{A}_{11} & \mathcal{A}_{12} \\ \mathcal{A}_{12} & \mathcal{A}_{11} \end{bmatrix} * \begin{bmatrix} \mathcal{B}_{11} \\ \mathcal{B}_{12} \end{bmatrix} \right) + \text{fold} \left(\begin{bmatrix} \mathcal{A}_{21} & \mathcal{A}_{22} \\ \mathcal{A}_{22} & \mathcal{A}_{21} \end{bmatrix} * \begin{bmatrix} \mathcal{B}_{21} \\ \mathcal{B}_{22} \end{bmatrix} \right) \\ \text{fold} \left(\begin{bmatrix} \mathcal{A}_{21} & \mathcal{A}_{22} \\ \mathcal{A}_{22} & \mathcal{A}_{21} \end{bmatrix} * \begin{bmatrix} \mathcal{B}_{11} \\ \mathcal{B}_{12} \end{bmatrix} \right) + \text{fold} \left(\begin{bmatrix} \mathcal{A}_{11} & \mathcal{A}_{12} \\ \mathcal{A}_{12} & \mathcal{A}_{11} \end{bmatrix} * \begin{bmatrix} \mathcal{B}_{21} \\ \mathcal{B}_{22} \end{bmatrix} \right) \end{bmatrix} \right) \\
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 &= \text{fold} \left(\begin{bmatrix} \text{fold} \left(\begin{bmatrix} \mathcal{A}_{11} & \mathcal{A}_{12} \\ \mathcal{A}_{12} & \mathcal{A}_{11} \end{bmatrix} * \begin{bmatrix} \mathcal{B}_{11} \\ \mathcal{B}_{12} \end{bmatrix} \right) + \text{fold} \left(\begin{bmatrix} \mathcal{A}_{21} & \mathcal{A}_{22} \\ \mathcal{A}_{22} & \mathcal{A}_{21} \end{bmatrix} * \begin{bmatrix} \mathcal{B}_{21} \\ \mathcal{B}_{22} \end{bmatrix} \right) \\ \text{fold} \left(\begin{bmatrix} \mathcal{A}_{21} & \mathcal{A}_{22} \\ \mathcal{A}_{22} & \mathcal{A}_{21} \end{bmatrix} * \begin{bmatrix} \mathcal{B}_{11} \\ \mathcal{B}_{12} \end{bmatrix} \right) + \text{fold} \left(\begin{bmatrix} \mathcal{A}_{11} & \mathcal{A}_{12} \\ \mathcal{A}_{12} & \mathcal{A}_{11} \end{bmatrix} * \begin{bmatrix} \mathcal{B}_{21} \\ \mathcal{B}_{22} \end{bmatrix} \right) \end{bmatrix} \right) \\
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 \end{aligned}$$

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Computations using Fourier Domain

Example: Consider two tensors $\mathcal{A} \in \mathbb{R}^{p \times q \times 3}$ and $\mathcal{B} \in \mathbb{R}^{q \times m \times 3}$ then

$$\mathcal{A} * \mathcal{B} = \text{fold} \left(\begin{bmatrix} A_1 & A_3 & A_2 \\ A_2 & A_1 & A_3 \\ A_3 & A_2 & A_1 \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ B_3 \end{bmatrix} \right) \in \mathbb{R}^{p \times m \times 3}$$

➤ Block circulant matrices can be diagonalized with the help of a normalized DFT matrix.

$$(F_n \otimes I_n) \text{bcirc}(\mathcal{A}) (F_n^* \otimes I_n) = \begin{pmatrix} D_1 & & & \\ & D_2 & & \\ & & \ddots & \\ & & & D_n \end{pmatrix} = \text{fft}(\mathcal{A}, [], 3),$$

$$F_n = \frac{1}{\sqrt{n}} \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & w & w^2 & \dots & w^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & w^{(n-1)} & w^{2(n-1)} & \dots & w^{(n-1)(n-1)} \end{bmatrix} \in \mathbb{C}^{n \times n}, w = \exp\left(-\frac{2i\pi}{n}\right)$$

Computations using Fourier Domain

Let $\mathcal{A} \in \mathbb{R}^{n \times n \times n_3 \times \dots \times n_p}$, we can write

$$(F_{n_p} \otimes F_{n_{p-1}} \otimes \dots \otimes F_{n_3} \otimes I_n) \cdot \text{bcirc}(\mathcal{A}) \cdot (F_{n_p}^* \otimes F_{n_{p-1}}^* \otimes \dots \otimes F_{n_3}^* \otimes I_n) = \begin{pmatrix} \Sigma_1 & & & \\ & \Sigma_2 & & \\ & & \ddots & \\ & & & \Sigma_\rho \end{pmatrix}$$

- Which is a block diagonal matrix with ρ blocks, where $\rho = n_3 n_4 \dots n_p$.
- Computation of tensors via the Fourier domain is obtained by systematically reorganizing the tensor into a matrix.
- The matrix computation results will be utilized for tensor computation.



Algorithm for t-Product

Introduction and
Motivation

Tensor Computation
(M-Product and
t-Product)

M-Product

t-Product

Image Applications

References

Algorithm 5: Product of two tensors with t-Product

- 1 **Input** $\mathcal{A} \in \mathbb{R}^{m \times n \times p}$, $\mathcal{B} \in \mathbb{R}^{n \times k \times p}$
 - 2 **Compute** $\overline{\mathcal{A}} = \text{fft}(\mathcal{A}, [], 3)$;
 - 3 **Compute** $\overline{\mathcal{B}} = \text{fft}(\mathcal{B}, [], 3)$;
 - 4 **for** $i \leftarrow 1$ to p **do**
 - 5 $\overline{\mathcal{C}}(:, :, i) = \overline{\mathcal{A}}(:, :, i) \overline{\mathcal{B}}(:, :, i)$
 - 6 **end for**
 - 7 **Compute** $\mathcal{C} = \text{ifft}(\overline{\mathcal{C}}, [], 3)$;
 - 8 **return** $\mathcal{C}$
-

Identity tensor

Identity tensor

The $n \times n \times n_3 \times \cdots \times n_p$ order- p ($p \geq 3$) identity tensor I is the tensor such that I_1 is the $n \times n \times n_3 \times \cdots \times n_{p-1}$ order- $(p-1)$ identity tensor and $I_j, j = 2, 3, \cdots, n_p$ is the $n \times n \times n_3 \times \cdots \times n_{p-1}$ order- $(p-1)$ zero tensor.

- The $4 \times 4 \times 3 \times 2$ identity tensor $\mathcal{I}$ has the following form

$$\mathcal{I} = \text{fold} \left(\begin{bmatrix} \mathcal{I}_1 \\ \mathcal{O}_2 \end{bmatrix} \right) = \text{fold} \left(\begin{bmatrix} \text{fold} \left(\begin{bmatrix} \mathcal{I}_{11} \\ \mathcal{O}_{12} \\ \mathcal{O}_{13} \end{bmatrix} \right) \\ \text{fold} \left(\begin{bmatrix} \mathcal{O}_{21} \\ \mathcal{O}_{22} \\ \mathcal{O}_{23} \end{bmatrix} \right) \end{bmatrix} \right)$$

- Here $\mathcal{I}_{11}$ is the 4×4 identity matrix and $\mathcal{O}_{ij}$ is a tensor all of whose components are zero.

Transpose of a tensor

If $\mathcal{A} \in \mathbb{R}^{n_1 \times n_2 \times \cdots \times n_p}$, then the transpose of $\mathcal{A}$, which is denoted by $\mathcal{A}^T$, is the $n_2 \times n_1 \times n_3 \times \cdots \times n_p$ tensor obtained by tensor transposing each $\mathcal{A}_i$, for $i = 1, 2, \dots, n_p$ and then reversing the order of the $\mathcal{A}_i$ from 2 through n_p ,

$$\mathcal{A}^T = \text{fold} \left(\begin{bmatrix} \mathcal{A}_1^T \\ \mathcal{A}_{n_p}^T \\ \mathcal{A}_{n_p-1}^T \\ \vdots \\ \mathcal{A}_2^T \end{bmatrix} \right)$$

Example of a transpose

- Let $\mathcal{A}$ be a $4 \times 4 \times 3 \times 3$ tensor. Then

$$\mathcal{A}^T = \text{fold} \left(\begin{bmatrix} \mathcal{A}_1^T \\ \mathcal{A}_3^T \\ \mathcal{A}_2^T \end{bmatrix} \right) = \text{fold} \left(\begin{bmatrix} \text{fold} \left(\begin{bmatrix} \mathcal{A}_{11}^T \\ \mathcal{A}_{13}^T \\ \mathcal{A}_{12}^T \end{bmatrix} \right) \\ \text{fold} \left(\begin{bmatrix} \mathcal{A}_{31}^T \\ \mathcal{A}_{33}^T \\ \mathcal{A}_{32}^T \end{bmatrix} \right) \\ \text{fold} \left(\begin{bmatrix} \mathcal{A}_{21}^T \\ \mathcal{A}_{23}^T \\ \mathcal{A}_{22}^T \end{bmatrix} \right) \end{bmatrix} \right)$$

- The transpose of the order-4 tensor $\mathcal{A}$ eventually reduces to some 4×4 matrix transpose.

f -diagonal tensor

f -diagonal

Let $\mathcal{A} = (a_{i_1 \dots i_p}) \in \mathbb{R}^{n_1 \times n_2 \times \dots \times n_p}$. Then, $\mathcal{A}$ is called an f -diagonal tensor if $a_{i_1 i_2 \dots i_p} = 0$ when $i_1 \neq i_2$. Further, $\{a_{i_1 i_2 \dots i_p} | i_1 = i_2\}$ are called the **t-diagonal** entries of $\mathcal{A}$.

Here f -diagonal $\rightarrow$ if each frontal slice is diagonal.

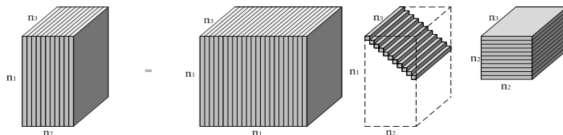
Let $\mathcal{A}$ be a $3 \times 4 \times 2$ tensor. Then

$$\mathcal{A} = \text{fold} \left(\begin{bmatrix} \mathcal{A}_1 \\ \mathcal{A}_2 \end{bmatrix} \right) = \text{fold} \left(\text{fold} \left(\begin{bmatrix} \mathcal{A}_{11} & 0 & 0 & 0 \\ 0 & \mathcal{A}_{22} & 0 & 0 \\ 0 & 0 & \mathcal{A}_{33} & 0 \\ \mathcal{A}_{11} & 0 & 0 & 0 \\ 0 & \mathcal{A}_{22} & 0 & 0 \\ 0 & 0 & \mathcal{A}_{33} & 0 \end{bmatrix} \right) \right)$$

Tensor Decomposition

Theorem (Tensor Singular Value Decomposition)

Let $\mathcal{A}$ be an $n_1 \times n_2 \times n_3$ real-valued tensor. Then $\mathcal{A}$ can be factored as $\mathcal{A} = \mathcal{U} * \mathcal{D} * \mathcal{V}^T$ where $\mathcal{U}, \mathcal{V}$ are orthogonal $n_1 \times n_1 \times n_3$ and $n_2 \times n_2 \times n_3$, respectively, and $\mathcal{D}$ is a $n_1 \times n_2 \times n_3$ f -diagonal tensor (each frontal slice is diagonal).



Suppose $\mathcal{A}$ is an $n_1 \times n_2 \times n_3$ and F_{n_3} is the $n_3 \times n_3$ DFT matrix. Then $T_{\text{circ}}(\mathcal{A})$ block circulant matrix, which can be block diagonalized, i.e., there exist matrices $\Sigma_1, \dots, \Sigma_n$ whose size is $n_1 \times n_2$, possibly with complex entries.

$$F_{n_3} = \frac{1}{\sqrt{n_3}} \begin{bmatrix} 1 & 1 & \dots & 1 \\ 1 & w & \dots & w^{n_3-1} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & w^{(n_3-1)} & \dots & w^{(n_3-1)(n_3-1)} \end{bmatrix} \in \mathbb{C}^{n_3 \times n_3}$$

Tensor Singular Value Decomposition

$$(F_{n_3} \otimes I_{n_1}) \cdot \text{Tcirc}(\mathcal{A}) \cdot (F_{n_3}^* \otimes I_{n_2}) = \text{diag}(\Sigma_1, \Sigma_2, \dots, \Sigma_{n_3})$$

Next, we compute the SVD of each Σ_i . Let $\Sigma_i = U_i \cdot D_i \cdot V_i^T$, for $i = 1, \dots, n_3$

$$\begin{pmatrix} \Sigma_1 & & \\ & \ddots & \\ & & \Sigma_{n_3} \end{pmatrix} = \begin{pmatrix} U_1 & & \\ & \ddots & \\ & & U_{n_3} \end{pmatrix} \begin{pmatrix} D_1 & & \\ & \ddots & \\ & & D_{n_3} \end{pmatrix} \begin{pmatrix} V_1^T & & \\ & \ddots & \\ & & V_{n_3}^T \end{pmatrix}$$

Apply $(F_{n_3}^* \otimes I_{n_1})$ to the left and $(F_{n_3} \otimes I_{n_2})$ to the right to the right of each of the block diagonal matrices.

We now have three block circulant matrices whose first block columns are $\text{unfold}(\mathcal{U})$, $\text{unfold}(\mathcal{D})$, and $\text{unfold}(\mathcal{V}^T)$.

Theorem-1

The Moore-Penrose inverse of a tensor $\mathcal{A} \in \mathbb{R}^{n_1 \times n_2 \times \dots \times n_p}$ exists and is unique.

Ref R. Behera, J. Sahoo, R. Mohapatra, M. Nashid. Computation of Generalized Inverses of Tensors via t-Product. *Numer Linear Algebra Appl.* 2021 DOI: 10.1002/nla.2416.



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Color image deblurring

- Consider $\mathcal{B} \in \mathbb{R}^{n \times n \times 3}$ is a blurred image, often corrupt with noise.

AIM: To establish a blurred free image.

- We write the image blurring problem

$$\mathcal{A} * \mathcal{X} = \mathcal{B},$$

where $\mathcal{A} \in \mathbb{R}^{n \times n \times 3}$ is a blurring tensor.

- **Need to construct** the blurring tensor.
- **Need to compute** $\mathcal{X} = \mathcal{A}^\dagger * \mathcal{B}$



Figure: Blurred image



Figure: Reconstruction image

Ref R. Behera, J. Sahoo, R. Mohapatra, M. Nashid. Computation of Generalized Inverses of Tensors via t-Product. *Numer Linear Algebra Appl.* 2021 DOI: 10.1002/nla.2416.

Color image deblurring

📖 The color image blurring problem $\mathcal{A} * \mathcal{X} = \mathcal{B}$, with size $n \times n \times 3$

$$(A^c \otimes A^h \otimes A^v) \begin{pmatrix} \text{vec}(X_{(1)}) \\ \text{vec}(X_{(2)}) \\ \text{vec}(X_{(3)}) \end{pmatrix} = \begin{pmatrix} \text{vec}(B_{(1)}) \\ \text{vec}(B_{(2)}) \\ \text{vec}(B_{(3)}) \end{pmatrix}, \quad (10)$$

Here the operation **vec** take an $n \times n$ matrix and return a $n^2 \times 1$ vector by stacking the columns of the matrix from left to right.

- $A^h \in \mathbb{R}^{n \times n}$ is the horizontal **within-channel** blurring matrices.
- $A^v \in \mathbb{R}^{n \times n}$ is the vertical **within-channel** blurring matrices.
- A^c is the **cross-channel** blurring matrix of size 3×3 as follows:

$$A^c = \begin{pmatrix} c_1 & c_3 & c_2 \\ c_2 & c_1 & c_3 \\ c_3 & c_2 & c_1 \end{pmatrix} \text{ with } \sum_{i=1}^3 c_i = 1 \text{ and } c_i \in \mathbb{R} \text{ for } i = 1, 2, 3.$$

Ref R. Behera, J. Sahoo, R. Mohapatra, M. Nashid. Computation of Generalized Inverses of Tensors via t-Product. **Numer Linear Algebra Appl.** 2021 DOI: 10.1002/nla.2416.

Color image deblurring

Following the circulant structure of the cross-channel blurring matrix, we can write

$$\mathcal{A} * \mathcal{X} * \mathcal{C} = \mathcal{B}, \quad (11)$$

■ $\mathcal{A}(:, :, k) = c_k A^v$, for $k = 1, 2, 3$ with $\mathcal{C}(:, :, 1) = (A^h)^T$ and $\mathcal{C}(:, :, j) = \mathbf{0}$, for $j = 2, 3$

We construct the blurring tensor $\mathcal{A}$ using the following symmetric banded Toeplitz matrix:

$$A_{ij}^v = A_{ij}^h = \begin{cases} \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(i-j)^2}{2\sigma^2}}, & |i-j| \leq k \\ 0, & \text{otherwise} \end{cases}$$



Figure: (a) True image (left), (b) Blurred noisy image (middle), (c) Reconstruction image (right).

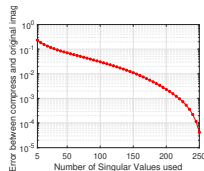
Image compression using SVD

- Since singular values are arranged in decreasing order and thus last terms of singular values have the least effect on the image.
- Consider a positive number k such that $k \leq r = \text{tubal rank} = \#\{i, \mathcal{D}(i, i, :) \neq 0\}$

$$\mathcal{A}_k = \sum_{i=1}^k \mathcal{U}(:, i, :) * \mathcal{D}(i, i, :) * \mathcal{V}(:, i, :)^T$$

$$\text{relative error} = \frac{\|\mathcal{A} - \mathcal{A}_k\|_F}{\|\mathcal{A}\|_F}$$

$$\text{where } \|\mathcal{A}\|_F^2 = \sum_{i=1}^l \sum_{j=1}^m \sum_{k=1}^n |a_{ijk}|^2$$



(a)

(b)

(c)

(d)

(e)

Figure: (a) True image; Reconstructions (b) 05 SVs; (c) 15 SVs (d) 25 SVs (e) 50 SVs.

Ref R. Behera, S. Maji, and R. Mohapatra. *Comp. Appl. Math.* 39, 284, (2020).

Hiding secret color images (video)

- Steganography is the technique of hiding data within an ordinary file to avoid detection and then extracting it at its destination.
 - $\mathcal{R}$ captures the **magnitude/intensity** information, the diagonal elements represent the **strength** or **importance** of each component
 - $\mathcal{L}$ captures the **directional/orientation** information of the image.



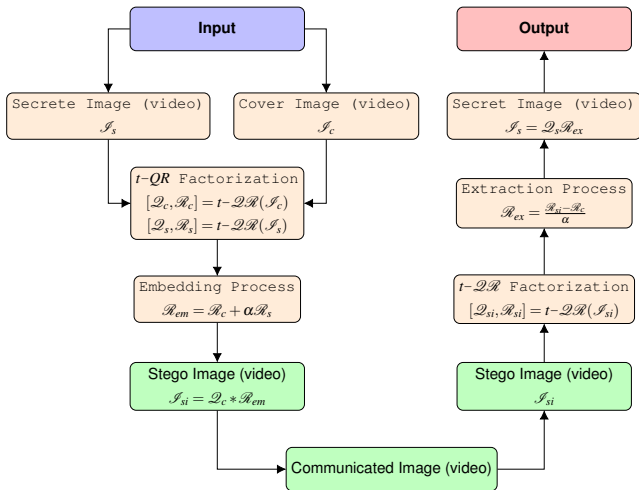
(a)



(b)

Figure: (a) Cover image, (b) Input secret image

Tensor-based steganography for data hiding



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Cover image and input secret image



Cover image and input secret image



Stego image and output Secret image



Stego image and output secret image

Secret color video analysis

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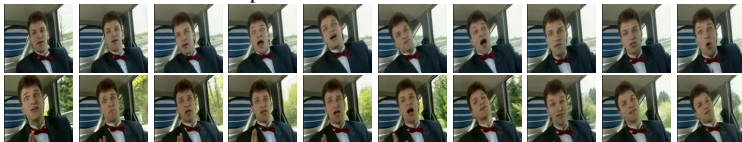
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Input secret video with 20 frames



Cover video with 20 frames



Output secret video with 20 frames





Measuring image quality

- Measuring quality assessment: peak signal-to-noise ratio (PSNR) and structural similarity index (SSIM) technique.
- We define the single PSNR of the color image and color video as:

$$PSNR = \begin{cases} 10 \times \log_{10} \left(\frac{max^2}{MSE} \right) & \text{for color image of size } m \times n \times 3. \\ 10 \times \log_{10} \left(\frac{max^2}{MSE} \right) & \text{for video of size } m \times n \times 3 \times p. \end{cases}$$

Here max represents the highest scale value of the 8-bits grayscale, i.e., $max = 255$.

📖 R. Behera, J. K. Sahoo, and Y. Wei. *Numer. Linear Algebra Appl.* 32 (1)(2025).

Measuring image quality

➤ MSE represents the mean square error of the tensor slices.

$$MSE = \begin{cases} \frac{1}{3mn} \left(\sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^3 [\mathcal{Z}_{(k)}(i,j) - \mathcal{A}_{(k)}(i,j)]^2 \right) & \text{for color image.} \\ \frac{1}{3mnp} \left(\sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^3 \sum_{l=1}^p [\mathcal{Z}_{(i,l)}(j,k) - \mathcal{A}_{(i,l)}(j,k)]^2 \right) & \text{for color video.} \end{cases}$$

➤ $\mathcal{Z}_{(k)}(i,j)$ and $\mathcal{A}_{(k)}(i,j)$ are the pixel values of the input and output images at the i,j coordinates of k th frontal slice.

➤ $\mathcal{Z}_{(k,l)}(i,j)$ and $\mathcal{A}_{(k,l)}(i,j)$ are the pixel values of the input color video and output color video at the (i,j) coordinates on k^{th} slice of l^{th} frame.

Measuring image quality

➤ We define structural similarity index measure (SSIM), following three main factors (luminance, contrast, and structure):

$$\text{SSIM}(\mathcal{X}, \mathcal{A}) = l(\mathcal{X}, \mathcal{A}) c(\mathcal{X}, \mathcal{A}) s(\mathcal{X}, \mathcal{A}), \quad (12)$$

$$l(\mathcal{X}, \mathcal{A}) = \frac{2\mathcal{F}_{\mathcal{X}}\mathcal{F}_{\mathcal{A}} + C1}{\mathcal{F}_{\mathcal{X}}^2 + \mathcal{F}_{\mathcal{A}}^2 + C2}, \quad c(\mathcal{X}, \mathcal{A}) = \frac{2\mathcal{G}_{\mathcal{X}}\mathcal{G}_{\mathcal{A}} + C2}{\mathcal{G}_{\mathcal{X}}^2 + \mathcal{G}_{\mathcal{A}}^2 + C2}, \quad s(\mathcal{X}, \mathcal{A}) = \frac{\mathcal{G}_{\mathcal{X}\mathcal{A}} + C3}{\mathcal{G}_{\mathcal{X}}\mathcal{G}_{\mathcal{A}} + C3}.$$

$$\mathcal{F}_{\mathcal{Z}} = \begin{cases} \frac{\sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^3 \mathcal{Z}_{(k)}(i,j)}{3mn} & \text{for color image.} \\ \frac{\sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^3 \sum_{l=1}^p \mathcal{Z}_{(k,l)}(i,j)}{3mnp} & \text{for color video.} \end{cases}$$

$$\mathcal{G}_{\mathcal{Z}}^2 = \begin{cases} \frac{\sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^3 (\mathcal{Z}_{(k)}(i,j) - \mathcal{F}_{\mathcal{Z}})^2}{3mn} & \text{for color image.} \\ \frac{\sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^3 \sum_{l=1}^p (\mathcal{Z}_{(k,l)}(i,j) - \mathcal{F}_{\mathcal{Z}})^2}{3mnp} & \text{for color video.} \end{cases}$$

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$$\mathcal{G}_{ZA} = \begin{cases} \frac{\sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^3 (\mathcal{Z}_{(k)}(i,j) - \mathcal{F}_{\mathcal{Z}}) (\mathcal{A}_{(k)}(i,j) - \mathcal{F}_{\mathcal{A}})}{3mn} & \text{for color image} \\ \frac{\sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^3 \sum_{l=1}^p (\mathcal{Z}_{(k,l)}(i,j) - \mathcal{F}_{\mathcal{Z}}) (\mathcal{A}_{(k,l)}(i,j) - \mathcal{F}_{\mathcal{A}})}{3mnp} & \text{for color video.} \end{cases}$$

$$\mathcal{F}_{\mathcal{A}} = \begin{cases} \frac{\sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^3 \mathcal{A}_{(k)}(i,j)}{3mn} & \text{for color image.} \\ \frac{\sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^3 \sum_{l=1}^p \mathcal{A}_{(k,l)}(i,j)}{3mnp} & \text{for color video.} \end{cases}$$

$$\mathcal{G}_{\mathcal{A}}^2 = \begin{cases} \frac{\sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^3 (\mathcal{A}_{(k)}(i,j) - \mathcal{F}_{\mathcal{A}})^2}{3mn} & \text{for color image.} \\ \frac{\sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^3 \sum_{l=1}^p (\mathcal{A}_{(k,l)}(i,j) - \mathcal{F}_{\mathcal{A}})^2}{3mnp} & \text{for color video.} \end{cases}$$

$$\mathcal{G}_{\mathcal{A}\mathcal{Z}} = \begin{cases} \frac{\sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^3 (\mathcal{A}_{(k)}(i,j) - \mathcal{F}_{\mathcal{A}}) (\mathcal{Z}_{(k)}(i,j) - \mathcal{F}_{\mathcal{Z}})}{3mn} & \text{for color image.} \\ \frac{\sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^3 (\mathcal{A}_{(k,l)}(i,j) - \mathcal{F}_{\mathcal{A}}) (\mathcal{Z}_{(k,l)}(i,j) - \mathcal{F}_{\mathcal{Z}})}{3mnp} & \text{for color video.} \end{cases}$$

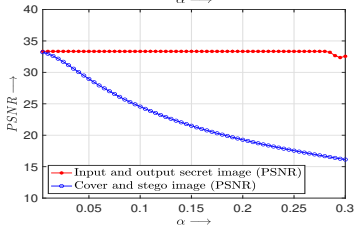
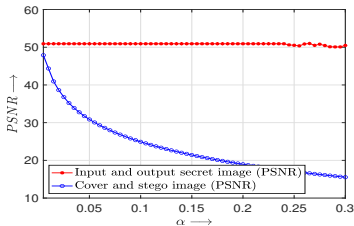
PSNR and SSIM Results

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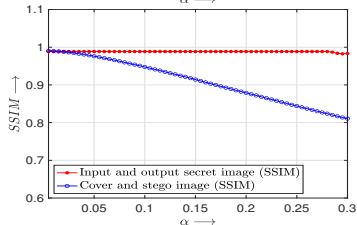
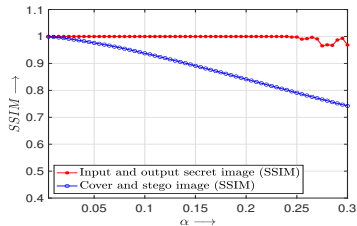
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The PSNR results for different values of α .



The SSIM results for different values of α .



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Thank You!!!